

Abstract

- Shared Memory configuration on Linux for 32-bit and 64-bit platforms
- · Virtual memory implementation in Linux kernel
- Linux kernel optimizations for Informix (virtual memory, network buffers, etc.)
- · RAW devices vs. block devices vs. flat files on Linux
- KAIO vs. Informix AIO on Linux;
- Linux specific problems with Informix (OOM killer, GLIBC compatibility, etc)





What Linux to choose?

- IDS is officially supported on Suse, RedHat, Asianux, Debian, Ubuntu
- IDS can't start in most Linux distributions, because of GLIBC incompatibility
- Suse and RedHat 'Enterprise' kernels are significantly better tested, that standard kernels
- Suse and RedHat are supported by majority of hardware vendors (SUN, IBM, HP, EMC, etc)
- · Suse and RedHat provide technical support for Linux
- Some parameters (e.g. default I/O scheduler) are better optimized for database usage





How to allocate memory to IDS

- 32-bit kernel can only address 3 GB of virtual memory for a single process
- 64-bit kernel allows to address 4 GB for 32-bit process
- IDS requires contiguous space for shared memory segments; most Linux distribution tend to map shared libraries starting at 1 GB (0x40000000) address:

This decreases the virtual address space by another 1GB; fixed in RedHat, configurable in Suse:

```
- ifmx@db1:$ echo 33554432 > /proc/$$/mapped_base
- ifmx@db1:$ oninit -v
- ifmx@db1:$ cat /proc/8545/maps
- 02000000-02016000 r-xp 00000000 08:01 96489 /lib/ld-2.3.3.so
- 02016000-02017000 rwxp 00016000 08:01 96489 /lib/ld-2.3.3.so
- ......
```

(only applicable to 32-bit kernel)



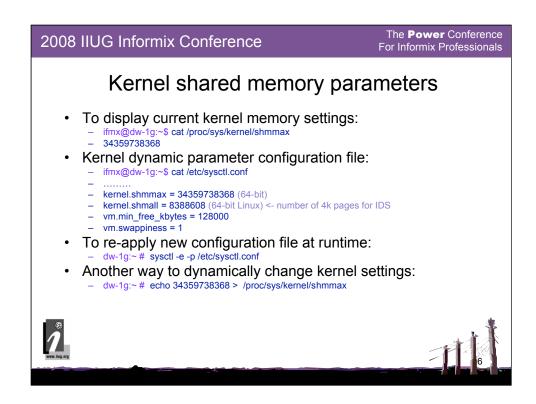
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32-bit IDS with 64-bit Linux kernel

- 32-bit IDS runs perfectly under 64-bit RedHat and Suse
- · Reasons to use:
 - Some DataBlades only exists in 32-bit versions
 - Krakatoa (Java UDR) only in 32-bit IDS 10
- · Advantages:
 - Possibility to allocate 4 GB of RAM to IDS
 - Significantly more stable, then 32-bit kernel
 - Possibility to combine Informix cache and file-system cache



If you need to run 32-bit IDS for some reason on Linux, consider running it under 64-bit kernel



This example shows parameters, used on machine with 32 GB of RAM

File system vs. Raw dev vs. Block dev

- O_SYNC flag for open() system call makes all writes synchronous

 IDS always uses this flag, that effectively makes file system and block devices as secure, as RAW devices!
- With Files system and block devices, all I/O reads and writes go through file system cache
- With RAW devices, no extra copying to file system cache is made for both reads and writes
- For file system, Linux cache buffer size is usually 4096 bytes;
- For block device, buffer size is 512 bytes
- · For each buffer, Linux (64-bit) allocates 96-byte buffer head structure
 - Huge waste of memory for block devices





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Direct I/O on Linux

- O_DIRECT flag was introduced in Linux 2.6
 - It makes all I/O operations go directly to applications buffers, without extra copying to OS cache (similar to RAW devices)
 - I/O size must be multiple of 512 bytes
 - Doesn't provide extra security vs. O_SYNC, provides memory optimizations
 - On Linux, works for both Block devices and files! (Block devices effectively turn into RAW devices, if opened with O_DIRECT)
 - Informix 10 uses this flag only for block devices, not files
 - Informix 10 only uses DIRECT with KAIO.
 (with KAIOOFF=1 block devices turn into REAL block devices!)
 - Informix 11.10 (Bug!!!) with block devices only uses O_DIRECT with AIOVP's (without KAIOOFF block devices turn into REAL block devices!)
 - IDS 11.10 can use O DIRECT with files (both KAIO and AIOVP's)
 - IDS 11.10 doesn't use O_DIRECT for TEMP dbspaces





What file system to use for IDS chunks?

- RaiserFS (never use for IDS chunks!!!)

 - Combination of database and File system;Optimized for storage of huge number of small files;
- EXT2: unjournaled file system

 - Very good database performancePotentially very long FSCK at Linux restart
- EXT3: data+metadata journaling ('data=journal' mount option)
 - Improves reliability at a performance penaltyDefault mount mode for EXT3
- EXT3: metadata-only journaling ('data=ordered' mount option)
 - Almost as fast, as EXT2 for normal DB operations
 Significant acceleration of FSCK

 - Extra data security over EXT2
- VxFS Veritas file system (commercial) good for read-mostly DB's



- Page journaling (data+metadata) inefficient for write-intensive DB's
- Optionally, provides 'raw' (uncached) mounting

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KAIO vs. traditional I/O

- Problem: read() and synchronous write() are blocking
- Solution #1: make I/O requests with set of processes Requires context switching
 Can give better 1/2

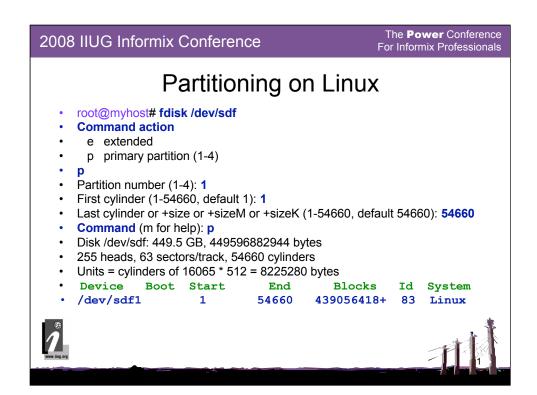
 - Can give better I/O overall throughput, then KAIO, when multiple concurrent random I/O requests are running
- Solution #2: use KAIO
 - Doesn't require context switching
 - Very good for situations, where latency is critical (sequential random I/0 e.g. data load or leaf index scan)
 - Requires result polling;
 - Possibly, multiple system calls are required to get a single result
 - Implemented in 2.6 kernel on Linux, first used in IDS 10.0 on Linux
 - If used, consider allocating more CPUVP's to IDS, then # CPU's!



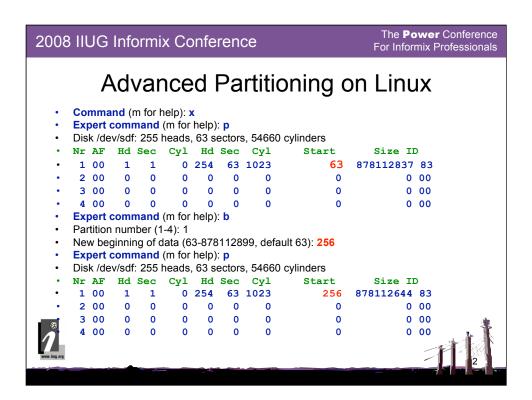


Most artificial benchmarks benefit from imroved latency, while majority of real-life systems benefit much more from overall I/O throughput.

My measurements of overall loads under highly parallel I/O activity demonstrated much better results with Informix I/O, then with KAIO



Linux partitioning in default mode...



This example shows, how to align Linux partitions for use with external SCSI or Fiber Channel arrays

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Virtual vs. physical drive geometry

- Modern hard drives report virtual, not physical CHS (cylinder-head-sector) geometry to OS and BIOS: 63 512-byte blocks per track
- BIOS and OS is historically using this information for partition table optimization: first partition starts on Virtual Cylinder #1
- All modern hard drives physically have Multi-zone geometry:
 - All physical cylinder are grouped into zones (15 zones typical)
 - Each zone has different number of sectors per track
- Smart arrays also report misleading geometry
 - Use of virtual drive geometry causes misalignment between IDS I/O units (2k pages) and internal array I/O units (4k or 8k pages)





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Creating raw devices on Linux

- · RAW devices were introduces in kernel 2.4
- · By default, Linux doesn't create RAW devices for disk partitions
- To create a RAW devices, one should use 'RAW' utility:
 - root@myhost# raw /dev/raw/raw1 /dev/sda1
 - /dev/raw/raw1: bound to major 8, minor 1
 - root@myhost# raw -qa
 - /dev/raw/raw1: bound to major 8, minor 1
 - root@myhost# Is -I /dev/sda1
 - brw-rw---- 1 root disk 8, 1 Jan 30 18:29 /dev/sda1
 - root@myhost# chown informix:informix /dev/raw/raw1
 - root@myhost# chmod 660 /dev/raw/raw1
 - root@myhost# In -s /dev/raw/raw1 /data/informix_data/chunk1
- After restart, Linux looses RAW devices (need redo in boot script)





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I/O schedulers on Linux

- Noop Scheduler
 - This scheduler only implements request merging.
 - Good for use with smart arrays
- Anticipatory IO Scheduler ("as scheduler")
 - default scheduler in older 2.6 kernels
 - Optimimized for sequential I/O never use for database!
- · Deadline Scheduler
 - preferred scheduler for database systems
- Complete Fair Queueing Scheduler ("cfq scheduler")
 - Default for Suse, RedHat, and for generic 2.6.18+

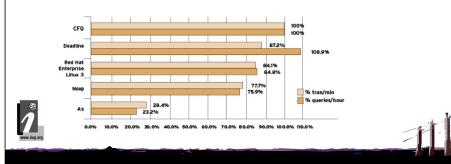




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I/O schedulers on Linux (cont.)

- · To display active scheduler:
 - root@myhost# dmesg | grep scheduler
 - Using cfq io scheduler
- · To configure scheduler at boot time:
 - 'Elevator=cfq' kernel boot parameter
- Effect of I/O scheduler on DB performance
 - (from http://www.redhat.com/magazine/008jun05/features/schedulers)



Memory management on Linux

- Linux kernel implements 'on-demand' physical memory allocation for user-space applications (when memory page is physically accessed)
- Linux kernel internally operates in physical memory
- Linux kernel allocates memory to application, disk cache buffers, internal kernel structures from FREE pool
- **KSWAPD** is a kernel thread (kernel-mode-only process), responsible for keeping FREE pool at constant level
 - Releases 'clean' buffer pool pages, not used for a long time
 - Swaps out application pages, not used for a long time
 - Swaps out application pages, not used for a long time
 Balance between these methods controlled by /proc/sys/vm/swappiness: Range (0-100), default '60', minimal swapping '0'
 Size of FREE zone is controlled by /proc/sys/vm/min_free_kbytes:
- - Default value is extremely low for machines with big memory (>1GB);
 - Low setting causes swapping, kernel errors and triggers OOM killer





NUMA-specific memory considerations

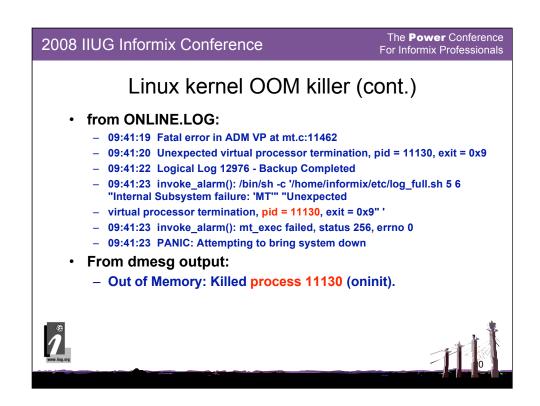
- On NUMA machines (e.g. multiprocessor Opteron machines), different CPU's have different access latencies to different memory banks;
- DB performance significantly degrades, if most actively accessed pages are allocated in a single bank;
- · Ways to avoid the problem:
 - BIOS-level 'memory inter-node interleaving'
 - OS-level memory allocation optimization (Implemented in RedHat 4, Suse 9,10, Solaris 10)





```
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                         Linux kernel OOM killer
        Fragment from /usr/src/linux/mm/oom_kill.c
         - /** oom_kill - kill the "best" process when we run out of memory
            * If we run out of memory, we have the choice between either
             * killing a random task (bad), letting the system crash (worse)
             * OR try to be smart about which process to kill. Note that we
             * don't have to be perfect here, we just have to be good. */
             static void oom_kill(void) {
                 p = select_bad_process();
                  /* Found nothing?!?! Either we hang forever, or we panic. */
                 if (p == NULL)
                      panic("Out of memory and no killable processes...\n");
                  /* kill all processes that share the ->mm (i.e. all threads) */
                 for_each_task(q) {
                      if (q->mm == p->mm)
                           oom_kill_task(q);
                                                }
            .....}
```

This is a self-explaining fragment from the Linux kernel source code



Linux kernel decided to kill Informix ADM VP process, because Linux needed to allocate memory for file system caching...

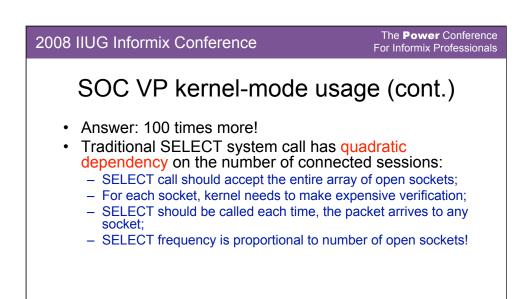
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SOC VP kernel-mode usage

- Single process, multiple connections problem:
 - Single process is listening to 10 connected sockets;
 - Each socket receives request 1 time per second
 - Each second, the process spends N milliseconds in kernel mode, polling TCP requests
- The number of clients changes from 10 to 100, same request rate from each client;
- How much time the process should spend in kernel mode, polling 100 connections?







It is not uncommon for poll threads to be 40% of CPU resources, consumed by Informix is very busy OLTP systems...

Configuring #Net VP's

- Sulution #1: distribute active sockets across multiple processes (Informix Net VP's)
- Never run TCP poll threads on CPUVP on heavily loaded OLTP systems
- How many NET VP's to configure? Standard approach:
 - Allocate 1 NET VP for each 100-200 connections
 - Doesn't work well in non-standard environment (e.g. Internet connection multiplexing)
- Alternative approach:
 - allocate as many NET VP's as necessary until NET VP CPU consumption drops below 10% of total CPU consumption





Informix MaxConnect

- Solution #2: Connection Multiplexing
- Informix MaxConnect reduces the number of connections by multiplexing multiple logical database client connection over a single physical network connection
- Should be located on a separate computer: upon first connection, consumes 100% CPU resources of the computer, running MaxConnect
- Has significant implications on multithreaded applications
- Not officially supported with IDS 10





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Epoll() on Linux & FASTPOLL in IDS 10

- Solution #3: Use EPOLL() instead of SELECT()
- · Epoll() is edge-triggered poll replacement for the 2.6 Linux:
 - Array of sockets is registered in kernel for event notifications;
 - Instead of socket list, array identifier is passed to the kernel
- Dramatically reduces kernel-time, required to poll connections;
- · Implemented in IDS 10.0XC5 on several platforms: Linux, Solaris
- Requires ONCONFIG parameter FASTPOLL=1
- Initial bug in 10.0FC5: FASTPOLL should not be used on HDR Secondary (fixed in 10.0FC6)





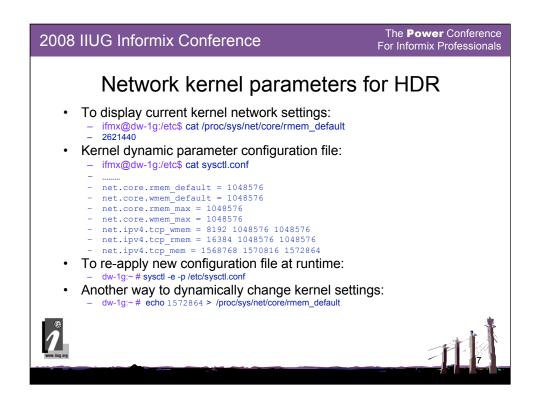
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Linux kernel network optimization

- Default Linux kernel network parameters are optimized for typical Client-Server environment:
 - Data blocks are relatively small (<32k);
 - Client doesn't send extra packet until server responds;
 - Server doesn't send package without request
- Streaming applications (Informix HDR):
 - Data blocks are relatively big;
 - Server can send extra block into a stream without delivery confirmation of the previous block







Streaming applications significantly benefit from increased kernel send and receive buffers. Both performance and reliability are improved.

